

# doppioDB: A Hardware Accelerated Database

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## ABSTRACT

Relational databases provide a wealth of functionality to a wide range of applications. Yet, there are tasks for which they are less than optimal, for instance when processing becomes more complex (e.g., matching regular expressions) or the data is less structured (e.g., text or long strings). In this demonstration we show the benefit of using specialized hardware for such tasks and highlight the importance of a flexible, reusable mechanism for extending database engines with hardware-based operators.

We present *doppioDB* which consists of MonetDB, a main-memory column store, extended with Hardware User Defined Functions (HUDFs). In our demonstration the HUDFs are used to provide seamless acceleration of two string operators, `LIKE` and `REGEXP_LIKE`, and two analytics operators, `SKYLINE` and `SGD` (stochastic gradient descent).

We evaluate *doppioDB* on an emerging hybrid multicore architecture, the Intel Xeon+FPGA platform, where the CPU and FPGA have cache-coherent access to the same memory, such that the hardware operators can directly access the database tables. For integration we rely on HUDFs as a unit of scheduling and management on the FPGA. In the demonstration we show the acceleration benefits of hardware operators, as well as their flexibility in accommodating changing workloads.

## 1. INTRODUCTION AND MOTIVATION

Relational engines exhibit great performance for a wide range of tasks. There are, however, well known operations and data types that cause problems. One of these data types is character strings which are both unstructured and expensive to process for anything but the simplest forms of pattern matching.

Most databases implement the SQL `LIKE` operator which can match multiple substrings divided by a wildcard `'%'`. For more complex string matching, some engines provide a vendor-specific regular expression operator, such as `REGEXP_LIKE`. In contrast to string matching with the `LIKE` op-

erator, regular expression evaluation is significantly more compute-intensive, easily resulting in a performance difference of an order of magnitude between the two operators.

With the increasing amount of user-generated data stored in relational databases, there is a growing need to analyze unstructured text data. At the same time, analytical operations in the context of machine learning become gradually more important to extract useful information from the vast amount of data collected. Many analytical operators incur a significant compute complexity not suitable to database engines where multiple queries share the available resources.

One way to address this trend is to use accelerators such as Xeon-Phi, GPUs, or FPGAs. Such approaches often promise orders of magnitude performance improvements, however in many cases the integration into a real system cancels these improvements because 1) the data needs to be adjusted to the execution model of the accelerator (e.g., GPUs, SIMD on Xeon Phi) and 2) the data needs to be partitioned between the host and accelerator memory. Indeed, the integration into the database and addressing challenges related to data consistency and management are still open problems.

Hybrid multicore architectures, such as IBM's CAPI for Power8 [5] and Intel's Xeon+FPGA platform [2], try to address these limitations. In these architectures, the accelerator is treated as another processor in the system and has direct access to shared memory. This architecture has the potential of removing both the data-reformatting and -partition overhead. In our work, we take advantage of this tight coupling and implement Hardware User Defined Functions (HUDFs) which can access data in the database without explicitly moving data to and from the accelerator. By implementing the UDF interface, the HUDF becomes just another operator from the point of the database engine and hides all the complexity of interacting with the hardware accelerator.

In this work we demonstrate the integration of the following three FPGA-based hardware operators into MonetDB, as explained in [4]: regular expression [4], skyline [6], and stochastic gradient descent [1]. The hardware operators are fully runtime parameterizable, i.e., the chip does not need to be reprogrammed for executing new queries using the same operator. Thanks to their integration into MonetDB as HUDFs, they can be used seamlessly in queries. As we will demonstrate, our FPGA-based operators achieve at least 2-3x speed up over software running on a 10-core CPU, reaching more than an order of magnitude improvement in many cases.

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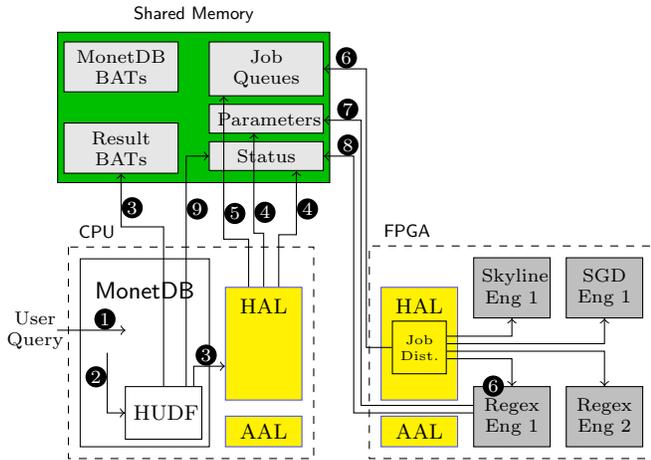


Figure 1: Overview of the system, the numbers show the steps of executing a regular expression query on the FPGA

## 2. SYSTEM OVERVIEW

The system used in the demonstration is described in [4]. It has three main components (Figure 1): 1) MonetDB extended with our Hardware User Defined Functions (HUDFs), 2) the *Hardware Operator Abstraction Layer* (HAL) providing a simple software API to execute jobs on the FPGA and 3) four hardware engines implementing one of the regular expression, skyline, or stochastic gradient descent operators. Each hardware engine is runtime parameterizable such that it can adapt to the current query.

### 2.1 MonetDB

We integrate hardware operators into MonetDB using its native UDF interface. Unlike most databases which require the invocation of the UDF for each tuple, in MonetDB UDFs can operate on complete columns, called binary association tables (BATs). To guarantee that the operators on the FPGA can access the data in MonetDB, we altered MonetDB’s memory allocation to use a custom memory allocator which manages the CPU-FPGA shared memory. In the current prototype system this region is limited to 4 GB, but this is not a fundamental limitation and will be lifted in future generations of the Xeon+FPGA system.

### 2.2 Hardware Operator Abstraction Layer

The HAL provides two main functionalities an API to construct and monitor jobs on the FPGA and the custom memory allocator for the CPU-FPGA shared memory region. After the initial handshake between software and hardware which is executed through Intel’s AAL (Accelerator Abstraction Layer) library, all control communication is handled by the HAL. The HAL allocates all control data structures such as the job queue, job parameters, and job status in the shared memory region, thereby they are accessible from software and hardware. Similarly all the BATs, data columns, and intermediate results of MonetDB and the result BATs produced by the FPGA are allocated in this region.

For each operator type a job queue is allocated in shared memory. When the HUDF in MonetDB creates a job through the HAL, a job is enqueued in the corresponding job queue. On the FPGA the *Job Distributor* is constantly monitoring

these queues and assigns new jobs to available engines of the requested operator type. The HAL module on the FPGA also arbitrates the memory access from the four engines to guarantee fair sharing of the available bandwidth.

### 2.3 Execution Walkthrough

We want to illustrate through an execution walkthrough the functionality of our system and the interaction of the three main components: MonetDB, HAL, and Hardware Engines. The walkthrough explains the execution of a regular expression query, but the same steps apply to other hardware operators. The following steps are required when processing a user query, while the corresponding numbers in Figure 1 show where in the system they take place:

1. A query containing a regular expression is submitted.
2. As part of executing the query, MonetDB calls the HUDF. The regular expression string and the input BAT are provided as parameters.
3. The HUDF allocates memory for the result BAT, and calls the HAL to create a new FPGA job.
4. The HAL allocates memory for the job parameters and job status data structures and populates them.
5. The HAL enqueues a job into the corresponding shared memory job queue.
6. The *Job Distributor* logic inside the HAL on the FPGA fetches the job from the job queue and assigns it to an idle Regex Engine (Engine 1 in this example).
7. The Regex Engine reads the parameters from shared memory and configures itself with the configuration vector. It then starts the execution and processes the input BAT.
8. After the engine terminates, it sets the `done` bit in its status memory and updates various statistics about the execution.
9. The UDF waits on the done bit and then hands the result BAT over to MonetDB.

Thanks to the standard UDF interface, HAL abstraction, and parameterizable hardware operators on the FPGA, a wide range of queries can be offloaded without reprogramming the FPGA.

### 2.4 Regular Expression Engines

Each regular expression engine is capable of processing strings at 6.4 GB/s, with up to four engines leading to an aggregated bandwidth of 25.6 GB/s. However on the current platform the throughput is limited by the QPI link to around 6.5 GB/s, therefore deploying more than one shows only a slight improvement and deploying more than two shows no further improvement. The regular expression engines are parametrized through a 512 bit configuration vector which is loaded by the Regex Engine before execution of each query. This configuration vector is generated on the software side in the HUDF, more details can be found in [4]. As a result the FPGA does not have to be reprogrammed to support multiple different queries.

### 2.5 Analytics Engines

The two analytics operators used for the demonstration are *SKYLINE* and *SGD* (stochastic gradient descent).

We integrated the skyline implementation by Woods et al. [6] into MonetDB as a HUDF. The skyline operator works on multiple columns and finds a list of records which are not

worse than any other (i.e. they are part of the pareto optimal set). A common example, is a query over hotels which have price and distance to the beach attributes. In this case, the skyline operator would return all hotels which are not worse than any other hotel for these two attributes. Skyline is an iterative, compute-bound operation with a variable runtime, similar to many machine learning algorithms. In our implementation the skyline operator can be parametrized at runtime to operate on up to 16 different attributes.

SGD is a very commonly used algorithm for training linear machine learning models. It is based on vector algebra, thus the inherent parallelism and deep-pipelined computation provided by an FPGA provides speedup over the state-of-the-art CPU implementations. We integrated an SGD operator into MonetDB as a HUDF, so that linear model training can be performed on newly imported or already existing data in relational tables. Through the HUDF interface, up to 16 features can be passed to the SGD operator. The operator is highly parameterizable (e.g., the convergence rate of the optimization, the frequency of model updates), such that the training can be tuned to the target data set to achieve an optimal convergence of the optimization problem [1].

### 3. DEMONSTRATION

#### 3.1 Setup

For our demonstration we use version 1 of the experimental Xeon+FPGA system released under the *Intel-Altera Heterogeneous Architecture Research Platform*<sup>1</sup> program [2].

The system has two sockets and each socket is its own NUMA region. One of them contains a 10-core CPU (Intel Xeon E5-2680 v2) and the other an FPGA (Altera Stratix V 5SGXEA). In this experimental system it is only possible to install memory in the CPU's NUMA region which is equipped with 96 GB of main memory. The FPGA has cache-coherent access to the memory through the QPI bus. This memory access is clearly bound by the available QPI bandwidth which we measured to be around 6.5 GB/s for read-intensive workloads. The reason for this low bandwidth is partially due to the prototype QPI endpoint which is implemented in FPGA logic and only runs at a frequency of 200 MHz. The QPI endpoint is part of the prototype system and cannot be modified. Based on announcements from Intel [3], we expect the memory bandwidth to increase significantly in the next generation of the platform.

The system runs Ubuntu 14.04 and a modified version of MonetDB (11.21.19) that includes all adaptations required to integrate the HUDFs.

#### 3.2 Scope and Presentation

During the demonstration, the user can interact through a web interface with the database. The interface consists of four tabs, one for each operator and a fourth where the operators can be combined in a workload experiment. The operator specific tabs allow to submit single queries, while in the workload tab multiple clients can be deployed to observe the effect of hardware acceleration on the system.

<sup>1</sup>Results in this publication were generated using pre-production hardware and software donated to us by Intel, and may not reflect the performance of production or future systems.

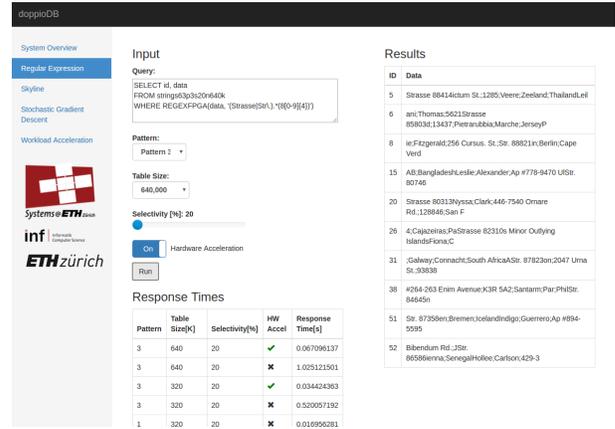


Figure 2: Single Query dashboard

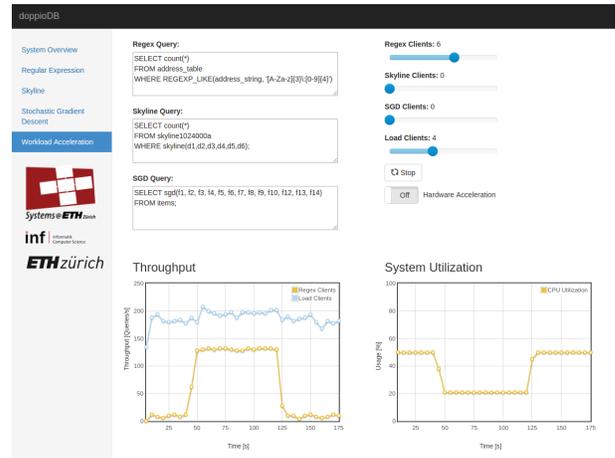


Figure 3: Workload acceleration dashboard, hardware acceleration was enabled between timestamp 40s and 120s

#### A) Single Query

Each operator has its own interface to run queries, the one for the regular expression operator is shown in Figure 2. The visitor of the demonstration will be able to choose among a varying number of queries and database tables which vary in regards to parameters such as pattern complexity, size of the table, selectivity, or number of dimensions. The queries can be executed either with hardware acceleration enabled or software-only. The visitor will see the different type of queries our system can handle and observe the effect of hardware acceleration through the reported response time. Additionally the results of the query are visualized in the UI to the visitor.

In the case of the regex operator we will illustrate that the operator can be used even if the patterns in the selection is too large to fit on the deployed regular expression circuit on the FPGA. To still benefit from hardware acceleration it can be executed in a hybrid mode where it is partially evaluated on the FPGA and partially in software. As the demonstration will illustrate, even a partial evaluation on the FPGA gives a significant performance boost over software-only evaluation.

## B) Workload Acceleration

The interface used for this part of the demonstration can be seen in Figure 3. The user can deploy four different type of clients. The first three types correspond to the available hardware operators. The fourth type executes simple queries to generate load on the system. The user can choose a different amount of clients from each type to create a workload. Since all three operators are already deployed, the FPGA does not have to be reprogrammed independent of the workload chosen. When the demonstration is running, the web interface will fetch in intervals of 5 seconds the aggregated throughput of the clients as well as the current CPU utilization. To see the impact of hardware acceleration, the visitor can enable and disable it while the clients are executing the queries. The impact can then be observed in real-time through the changes observed in the graphs.

## 4. INSIGHTS FOR THE DEMO VISITORS

The demonstration will convey the insights we gathered related to the benefits and drawbacks of using UDFs to interface with the accelerator. The abstraction of Hardware User Defined Functions (HUDFs) provides a seamless integration of hardware operators and hides the complexity of offloading to an accelerator from the database engine. This makes it possible to use the accelerator in many scenarios, and even compose its results easily with software operators (i.e. in the case of hybrid execution of regular expressions).

However the UDF interface also imposes some limitations, for instance depending on the database only one tuple at a time can be passed to the UDF, or the number of tables or columns a UDF can operate on is usually limited. An other important drawback, especially since we use UDFs to hide an accelerator, is that from the point of the database engine the UDF acts like a black box. Thereby making any predictions about its execution cost or runtime nearly impossible.

However, information regarding the accelerator such as capacity, current load, and a performance model are all available and could be made available to the database engine. By exposing the accelerator as a more transparent unit the query optimizer would be able to build a cost model. Thereby the optimizer can also decide if calling the accelerator indeed accelerates the execution. If, for instance, an accelerator is fully utilized but CPU utilization is low, it

might be beneficial to execute the operator in software instead of offloading it. To achieve a better integration with the query engine, the HUDF interface has to be extended further and the execution model of the accelerator has to be made available to the database engine. We plan to address these challenges in future work.

As for the choice of platform, in our work we used an Intel Xeon+FPGA system, one of the first high-performance shared-memory hybrid architectures. Given the announcements of future Xeon+FPGA systems [3] or the development of cache-coherent interfaces for accelerators such as OpenCAPI and CCIX, we expect to see more hybrid systems and an even tighter integration between accelerators and CPUs. As we have shown in this work, databases can benefit significantly from hybrid shared memory architectures, especially in regards to compute-intensive operations, and this benefit will only increase with tighter integration.

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